

Quiz #4 (CSE4190.410)

October 19, 2011 (Wednesday)

1. (10 points) In the line drawing algorithm of Bresenham, derive the initial value

$$p_0 = 2\Delta y - \Delta x$$

$$\begin{aligned} p_0 &= \Delta x(2m(x_0 + 1) - 2y_0 + 2b - 1) \\ &= \Delta x(2(mx_0 + b) + 2m - 2y_0 - 1) \\ &= \Delta x(2y_0 + 2m - 2y_0 - 1) && \because y_0 = mx_0 + b \\ &= \Delta x(2m - 1) \\ &= \Delta x\left(2\frac{\Delta y}{\Delta x} - 1\right) && \because m = \frac{\Delta y}{\Delta x} \\ &= 2\Delta y - \Delta x \end{aligned}$$

2. (10 points) Consider a rotation R_1 about an axis $(0, 1, 0)$ by angle 60° and another rotation R_2 about an axis $(0, 0, 1)$ by angle 60° . What is the axis and angle of the composite rotation R_1R_2 ?

$$q_1 = \left(\frac{\sqrt{3}}{2}, 0, \frac{1}{2}, 0\right)$$

$$q_2 = \left(\frac{\sqrt{3}}{2}, 0, 0, \frac{1}{2}\right)$$

$$\begin{aligned} q_2 \cdot q_1 &= (\omega_2\omega_1 - \langle (x_2, y_2, z_2), (x_1, y_1, z_1) \rangle, \omega_2(x_1, y_1, z_1) + \omega_1(x_2, y_2, z_2) + (x_2, y_2, z_2) \times (x_1, y_1, z_1)) \\ &= \left(\frac{3}{4}, -\frac{1}{4}, \frac{\sqrt{3}}{4}, \frac{\sqrt{3}}{4}\right) = \left(\frac{3}{4}, \frac{\sqrt{7}}{4}, -\frac{1}{\sqrt{7}}, \frac{\sqrt{3}}{\sqrt{7}}, \frac{\sqrt{3}}{\sqrt{7}}\right) \end{aligned}$$

$$\text{axis: } \frac{1}{\sqrt{7}}(-1, \sqrt{3}, \sqrt{3})$$

$$\text{angle: } 2\arccos\left(\frac{3}{4}\right)$$